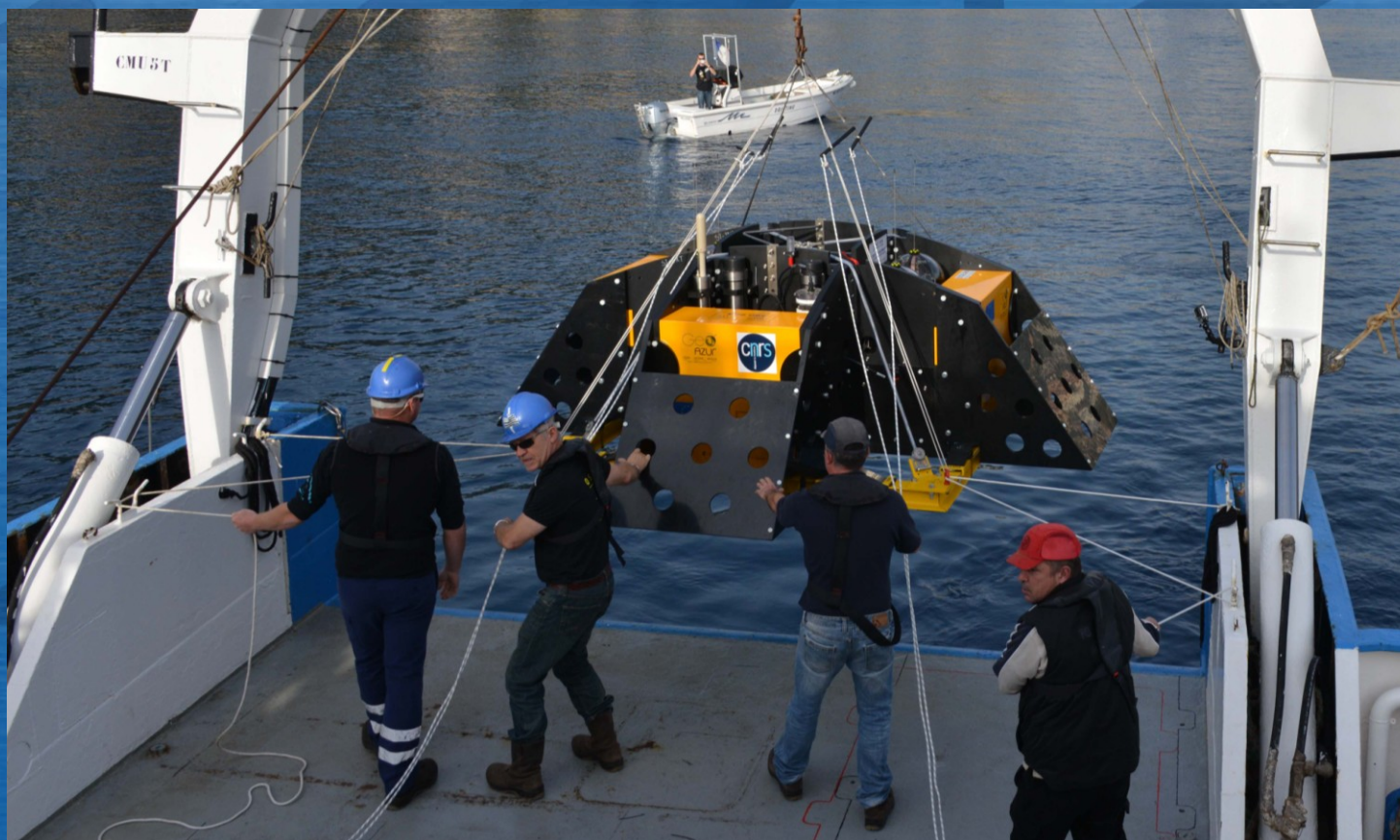


# MUG-OBS - Multiparameter Geophysical Ocean Bottom System

- A new instrumental approach for monitoring earthquakes.





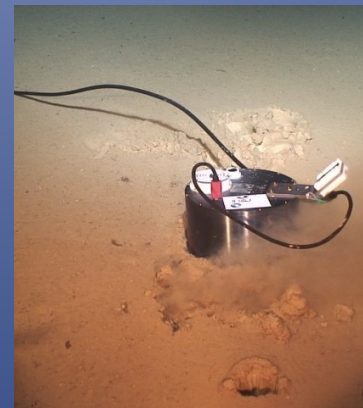
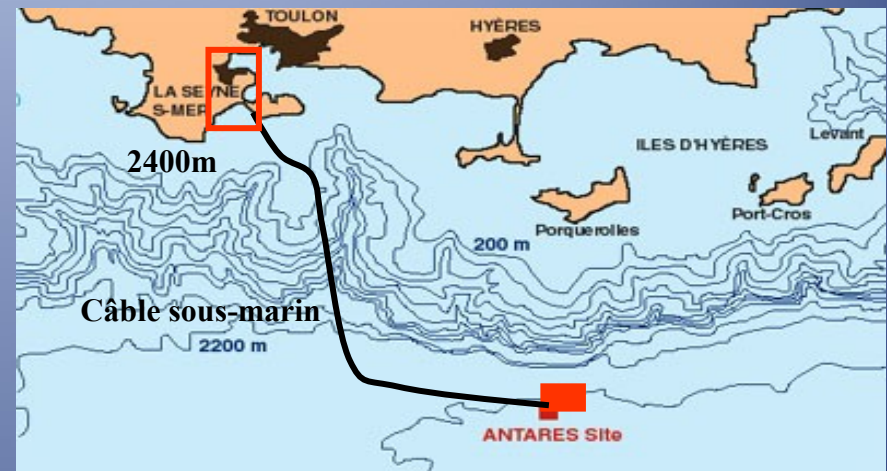
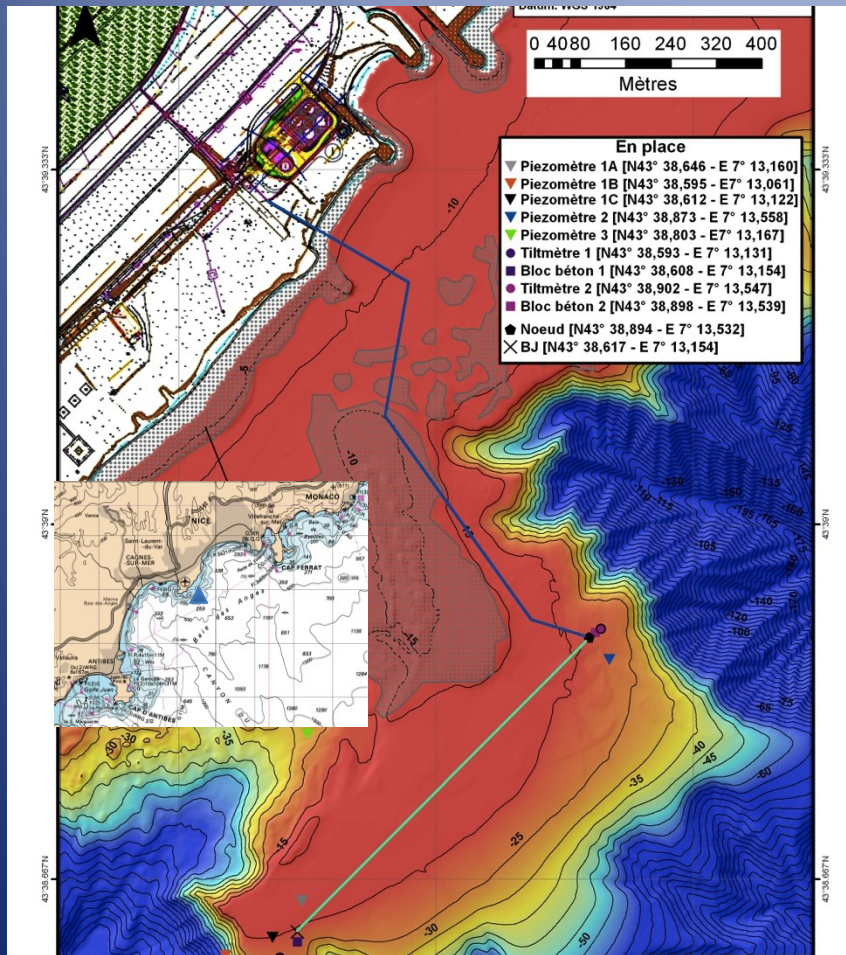
Real time cabled OBS are part of larger Observatories (Donet/Neptune), installed on limited sites – Installation is heavy and expensive.

BroadBand Sensor is installed and buried by ROV





# Real Time two Broadband Cabled seismometer in Mediterranean



CMG3T/5T Guralp  
Broad Band

OBS – Short Term Network, few months to a year or two with no control of data quality and costly to operate in shiptime and human's resources

Hippocampe-Geoazur



OBS Scripps



OBS GEOMAR



MicroOBS Ifremer

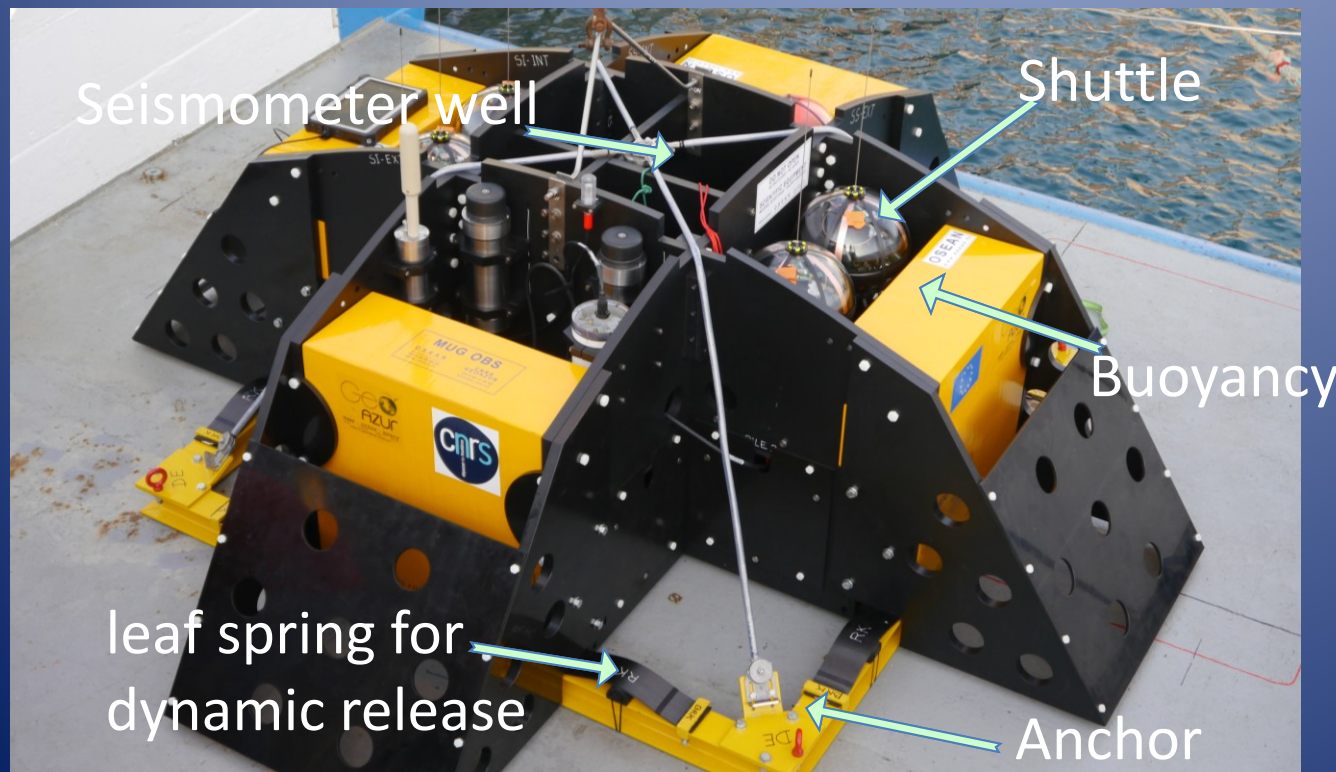
An attempt to isolate the Broadband sensor from the chassis for a better coupling and response.



MUG is an alternative to real time observatory and short time  
OBS Network.

MUG-OBS is ideally suited to study subduction zones

Once installed we control the main parameters and data quality and  
later using a small vessel of opportunities recover data within  
autonomous shuttles released by acoustic,



#### DIMENSIONS

2.9m x 2.9m x 1m.

Shaped to resist a trawling

#### MATERIAL

Non conductive material  
(Syntactic foam, Polyethylene,  
glass and Titanium)

#### Dead Weight Anchor

Steel with anodes

#### Weight in Air

1.5t (3307Lb)

Dead Weight

## MUG landing at bottom of the sea.



### DEEP OCEAN

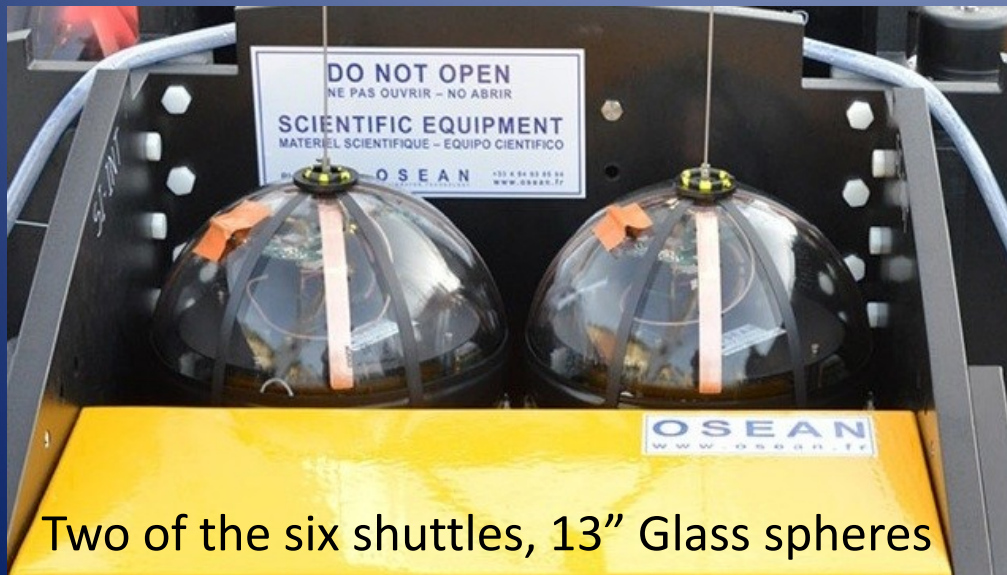
- 6000m depth rated (19,685Ft).

### LONG AUTONOMY

- More than 3-years Autonomy (42 month - LiSo<sub>2</sub> batteries encapsulated in three containers).

### COST EFFECTIVE & INNOVATIVE

- 6 data shuttles with acoustic release. Redundancy for data back-up in the shuttles.

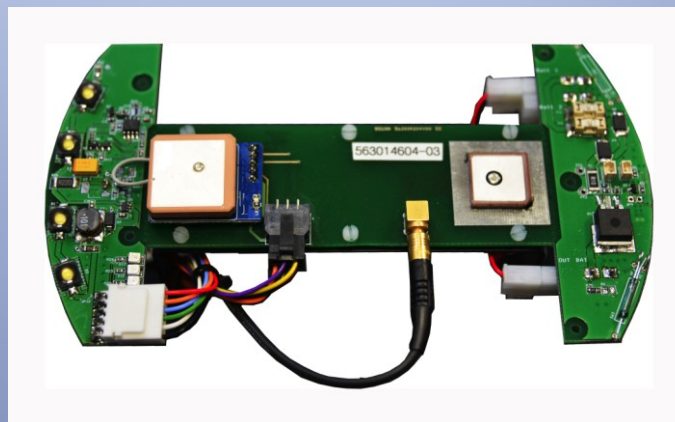
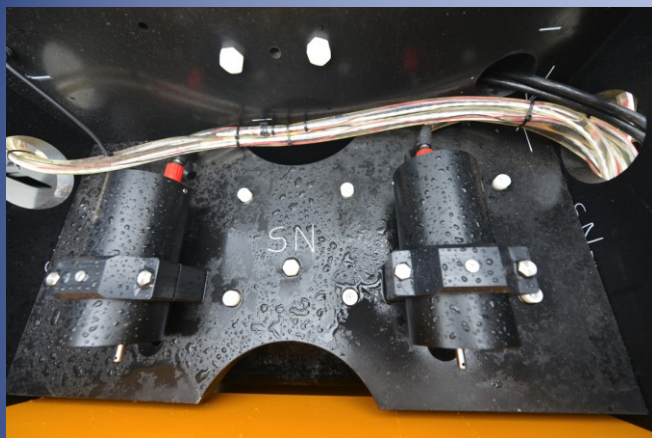


Two of the six shuttles, 13" Glass spheres

### TIME MANAGEMENT

- $1.10^{-8}$  Real Time Clock.
- GPS Automatic time drift measurement when surfacing.





GPS / AIS/ Iridium/strobe light.



Digital Inductive communication

Shuttle at release heading to the Surface.



Shuttle at Surface.

## 6 SHUTTLES

### DATA COMMUNICATION

Wireless Digital Inductive communication Station / Shuttles

### TIME MANAGEMENT

- $1.10^{-8}$  Real Time Clock.
- GPS Automatic time drift measurement when surfacing.

### SHUTTLES LOCALIZATION

- GPS / AIS
- STROBE LIGHT

### DATA STORAGE

- A year

### DATA TRANSMISSION

self-bulletin of detected major events by Iridium.

# Acoustic communication and localization

GPS / AIS  
localization

GPS / Iridium  
antenna

Strobe light



Two acoustic containers

## ACOUSTIC COMMUNICATION

- 2 independent channels in
- Two independent containers
- Diagnostic (Health bulletin)
- Distance & Positioning
- MUG and shuttle trigger for recovery.

## STATION LOCALIZATION

- GPS / AIS / Iridium
- Strobe light

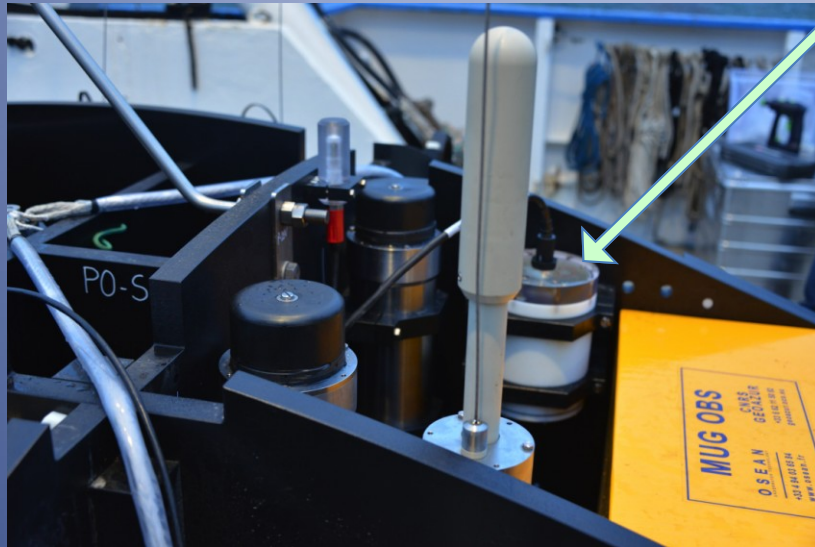
## PROGRAMMATION & PARAMETERS CONFIGURATION

- Ethernet Web Server
- GPS & NTP
- Optical Cable interface for real time application.



# Sensors and communication

DPG - Scripps



## SENSORS

Type	Sampling rate
- 3-axis 120s Velocimeter Trillium	100Hz
- 3-axis Accelerometer	100Hz
- Broadband hydrophone	100Hz
- Absolute Pressure	30s
- Differential Pressure	100Hz
- 3-Axis Magnetometer for signal Orientation	
- 2-Axis Tiltmeter on chassis.	
- Temperature	
- Humidity	

## DATA MANAGEMENT

More than 3 years (42 month)  
continuous recording on SD-Flash  
memories.

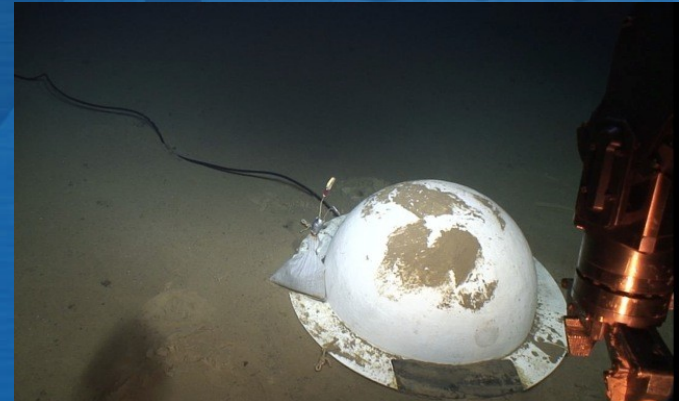
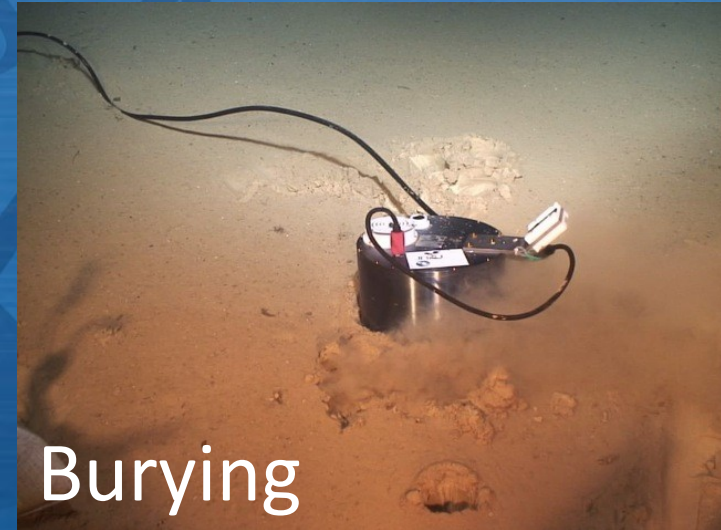
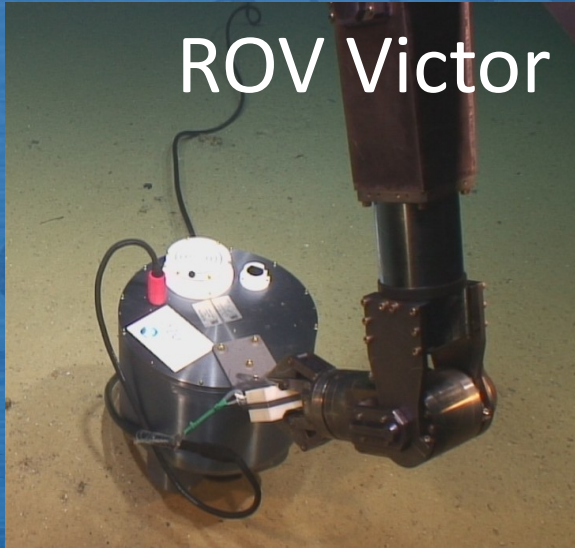
Data format:

RAW/MiniSEED/SAC



Absolute Pressure

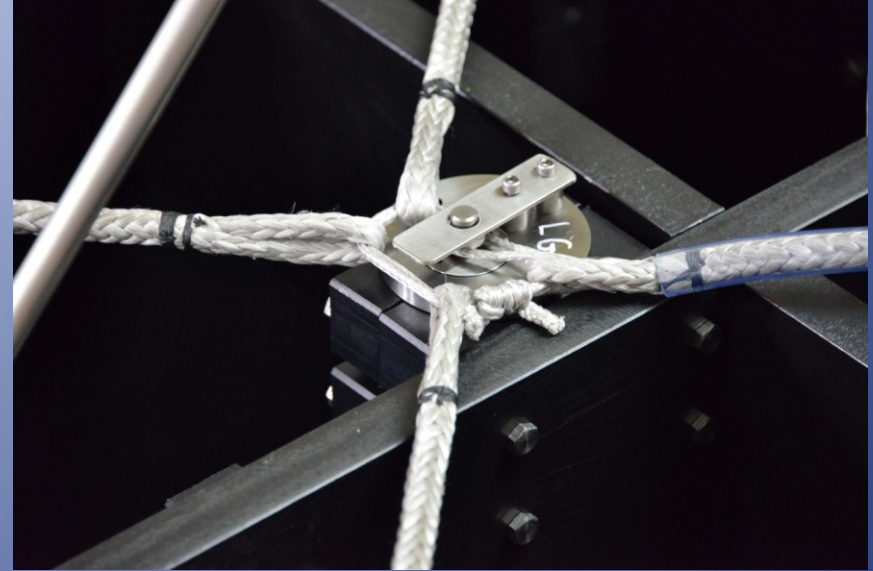
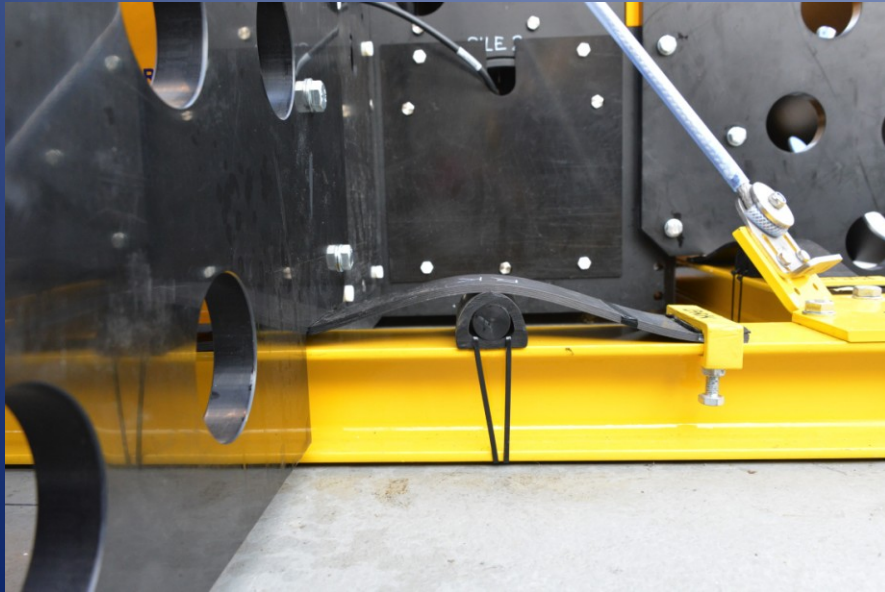
# B-Band seismometer – Consideration for installation





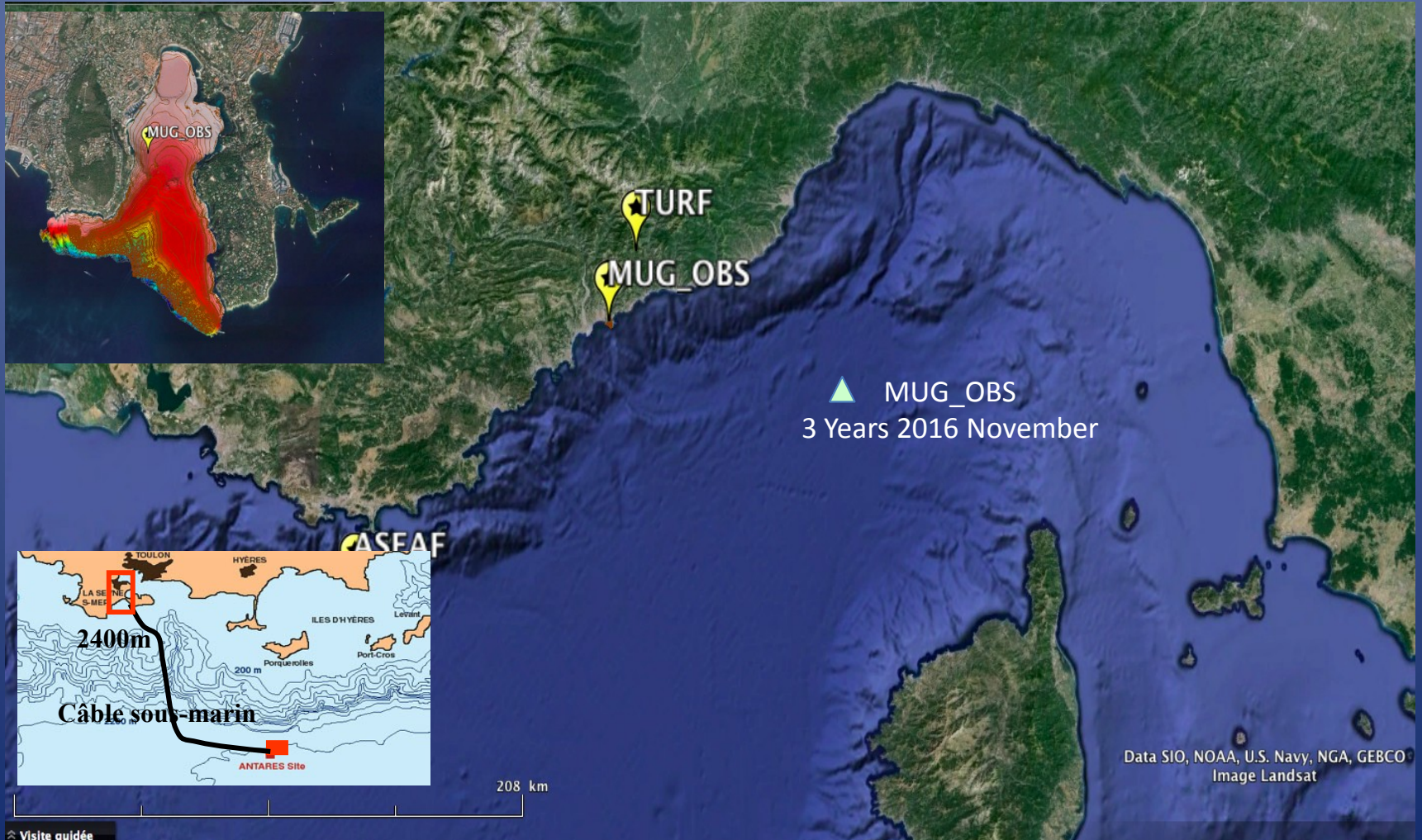
# New features and specifications

- Main sensor is located inside a well, protected against current convection by top flaps and dissociated from the housing.
- Main sensor is released and activated by acoustic or timer.
- Main release is located on top of the station to avoid corrosion over long term deployment.



- 200 l for Buoyancy made of syntactic foam.
- Dynamic release system:  
8 x 25kg leaf spring additional force

# Tests Campaigns November 2015 and March 2016



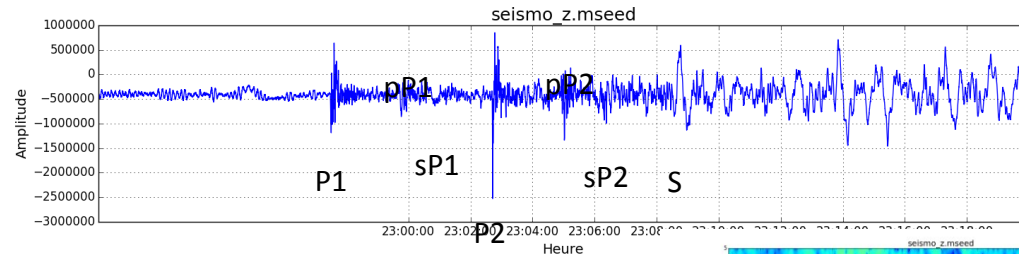


First recorded events during sea trial carried out at  
Villefranche sur mer - Depth 30m.

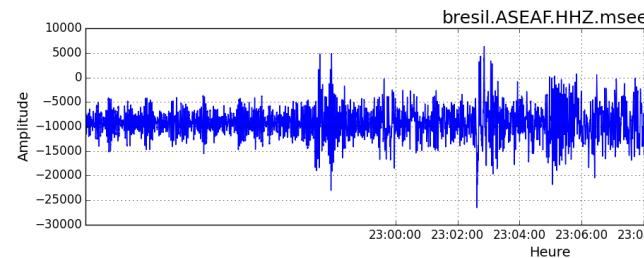
2015/11/24 at 22:45:38 “foreshock” 7.4 magnitude and  
2015/11/24 at 22:50:53 “Perou” 7.6 magnitude

2015/11/24 complete sequence

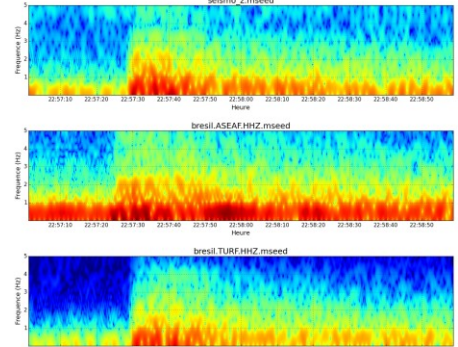
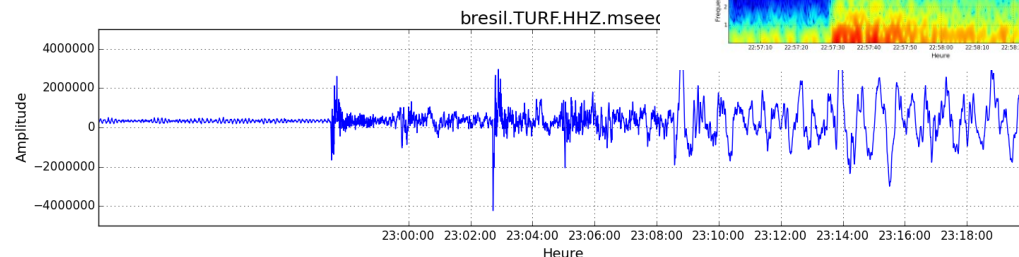
MUG Vertical  
velocity



Real Time CMG3T-  
Antares cabled OBS  
Vertical velocity



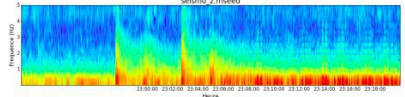
TURF – Land  
Station  
Vertical  
velocity



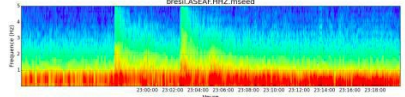
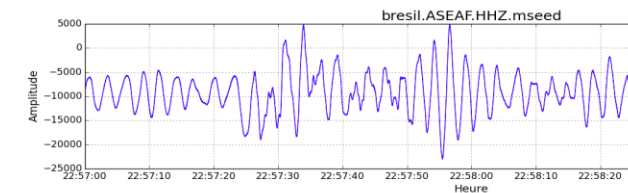
# Details of the two events Perrou 2015/11/24

2015/11/24 at 22:45:38 - 1st Event

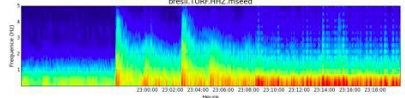
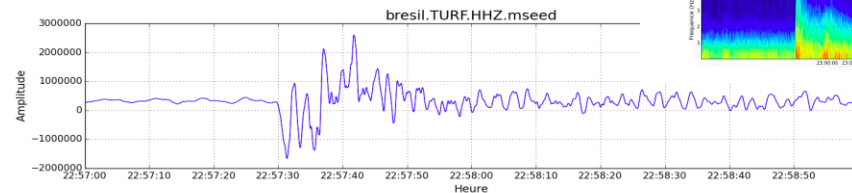
MUG Vertical velocity



Real Time CMG3T- Antares  
cabled OBS Vertical velocity

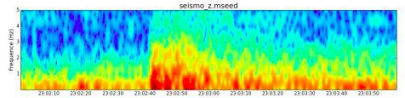


TURF – Land Station  
Vertical velocity

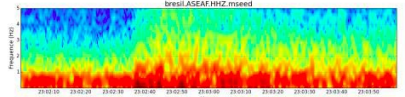
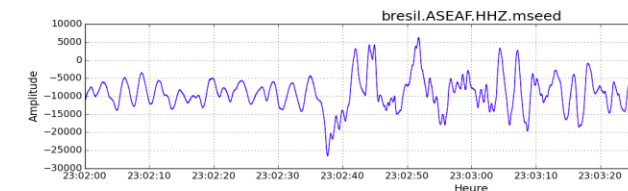


2015/11/24 at 22:50:53 – 2<sup>nd</sup> Event

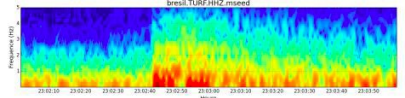
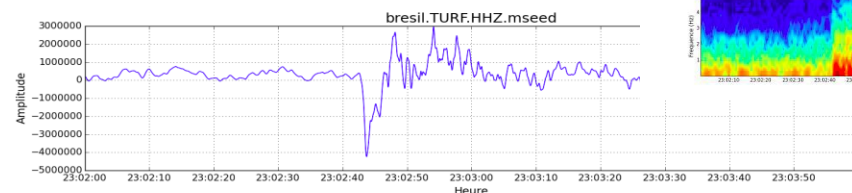
MUG Vertical velocity



Real Time CMG3T- Antares  
cabled OBS Vertical velocity

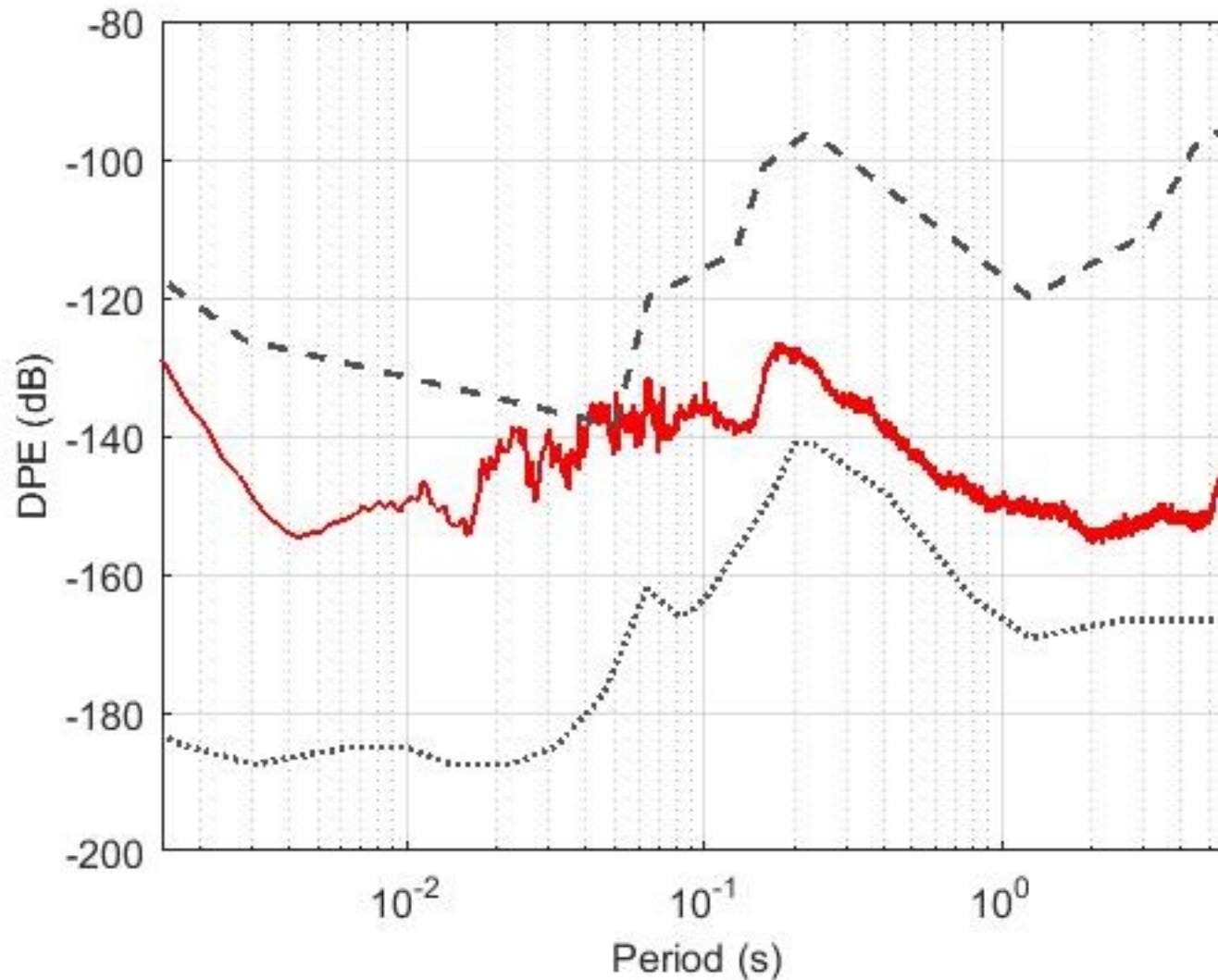


TURF – Land Station  
Vertical velocity

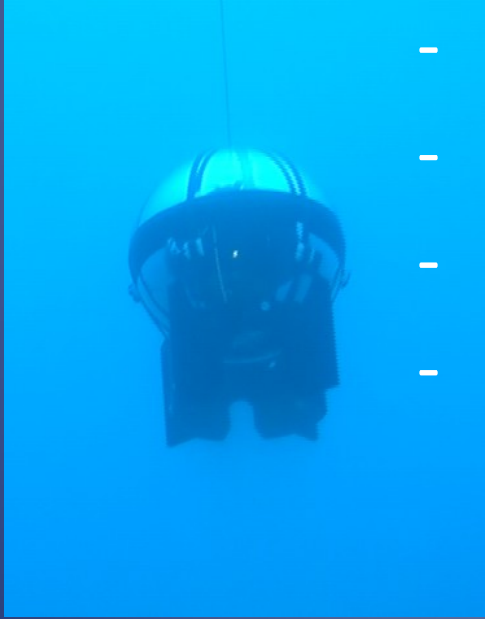




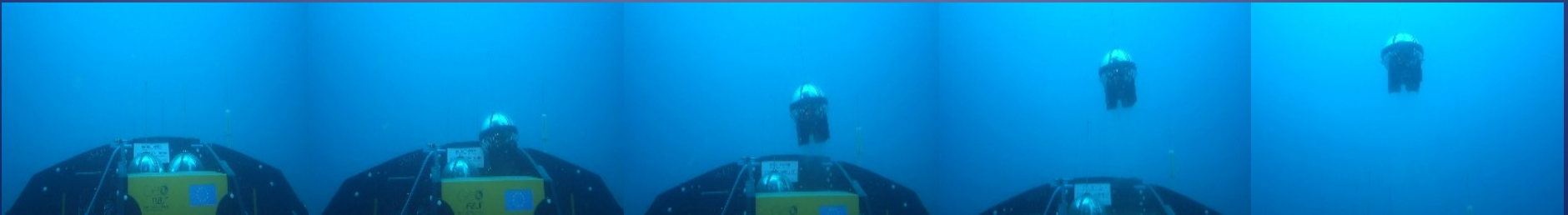
# Low Noise Model



# MUG\_OBS main improvements.



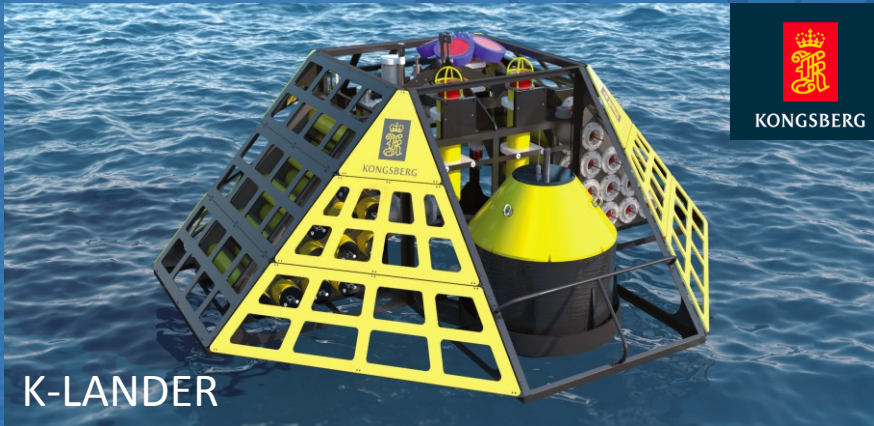
- Use of Shuttles reduce the cost of ship-time
- and lowered the cost for recovering data.
- Data are collected on demand.
- Long term MUG\_OBS is the appropriate tool to meet the criteria for the:  
Subduction Zone Observatory project.



Shuttle release sequence

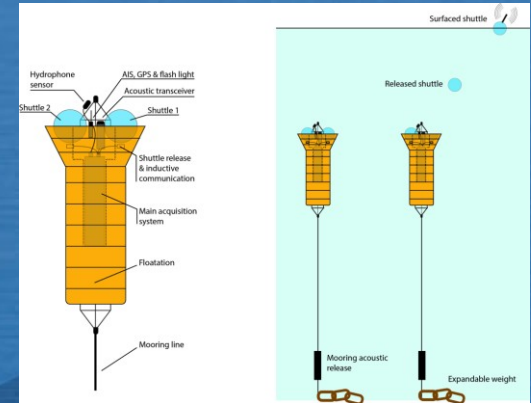


# MUG - Multidisciplinary Platform

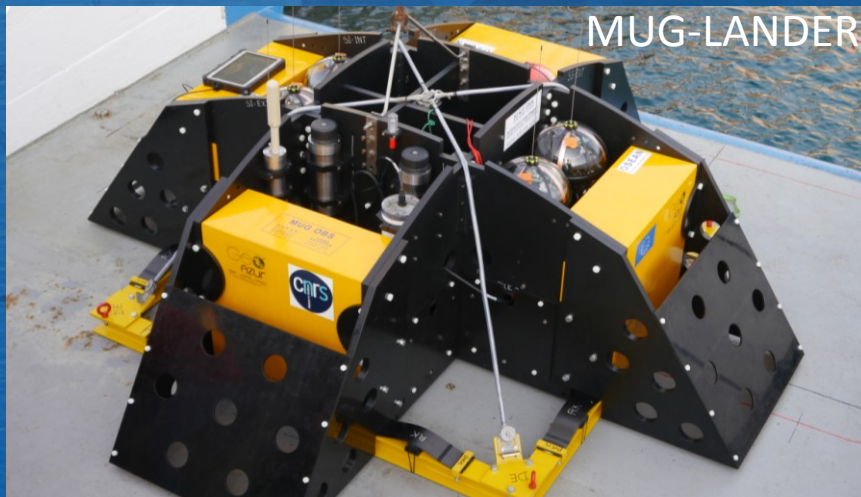


K-LANDER

- Rated 2000m Max
- **RECOVERY DEPTH** Depending on rope length and currents in deployment area



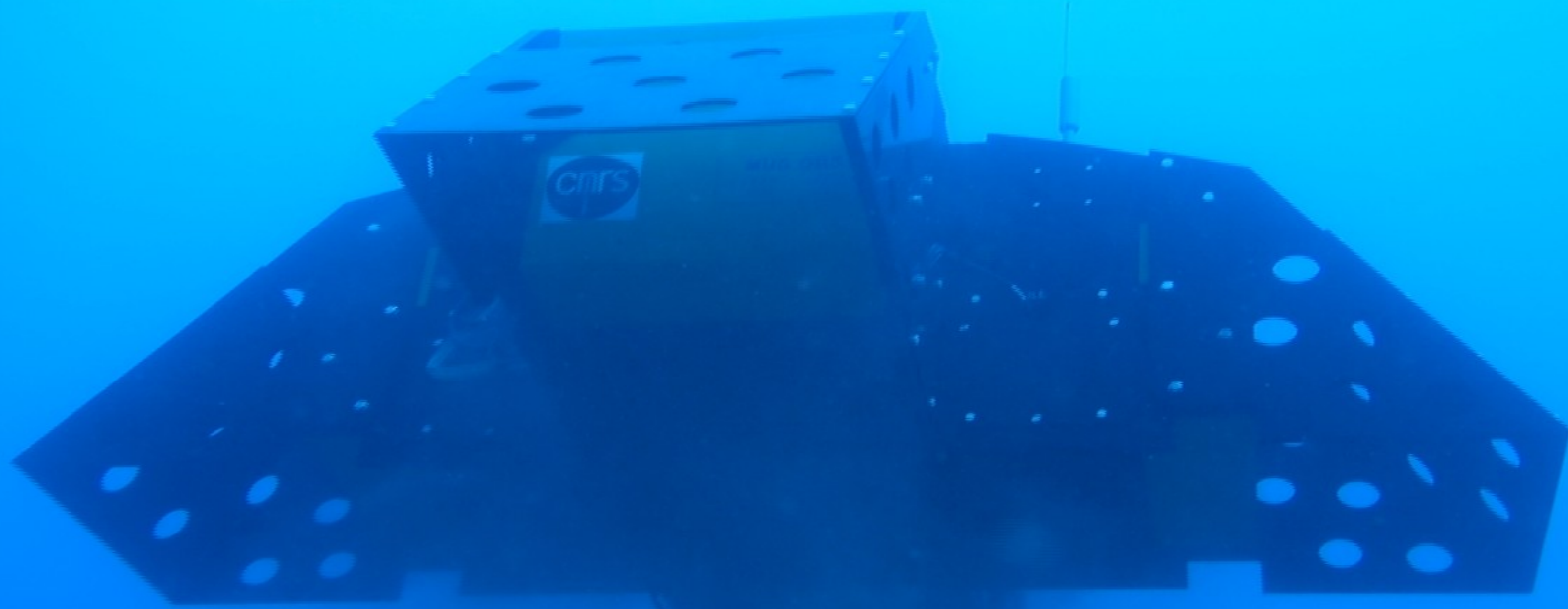
Mooring Hydroacoustic measurements for seismology and Mammals detection



MUG-LANDER

Environmental , biological and Physics Sensors for Oceanographie.

- CH4 Contros HydroC™ CH4
- CO2 Contros HydroC™ CO2
- Kongsberg Workhorse Long Ranger 75 kHz ADCP
- SBE41 - CTD
- Bband (10s – 50 Khz) Hydrophone



# Thank you for your attention.

Y.Hello; P.Charvis; Diane Rivet - Geoazur

Manuk Yegikyan; Romain verfaillie - Osean SAS



